INTEGRATED CIRCUITS

IF quadrature transceiver

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IC17 Data Handbook

PHILIPS

DESCRIPTION

The SA1630 is a 70–400 MHz I/Q transceiver for wireless LAN. The Receive Path contains a digitally gain controlled linear IF amplifier, a pair of quadrature down conversion mixers and a pair of baseband amplifiers. The transmit path contains a pair of quadrature up conversion mixers that transposes a quadrature baseband input signal up to IF frequency. An external VCO signal is divided internally and provides quadrature local oscillator signals for the mixers. Another divider chain, reference divider and phase detector are provided to avoid the need for an external synthesizer. To keep power consumption to a minimum the transmit, receive and local oscillator functions can be powered down under digital control.

FEATURES

- Low supply voltage operation of 2.7V for main chip and 2.9V for charge pump.
- Low current consumption: 33.5 mA in RX, 26.5 mA in TX, typical at 3V.
- Flexible power up/down options.
- Optional 2.5V regulated reference voltage available during transmit.
- Input IF frequency range of 70–400 MHz.
- Internal IF PLL for synthesizing the local IF oscillator signal.
- Bandwidth of baseband Tx inputs is 20 MHz and that of baseband Rx outputs is 8.5MHz.
- Designed for IEEE 802.11 wireless LAN using Direct Sequence Spread Spectrum modulation.
- Control registers power up in a default state.
- Only a standard reference input frequency required, choice of 8, 11, 22 or 44 MHz.
- Digital gain control of 70 dB in steps of 2 dB.
- \bullet Rx Baseband amplifiers are capable of driving 1k Ω ||15pF
- Rx Baseband o/p's clamp symmetrically, above 1Vp–p in order to prevent dc bias shift under overdrive conditions.
- Package: LQFP–48, PCMCIA compatible

APPLICATIONS

- IF circuitry for IEEE 802.11 DSSS wireless LAN.
- Applications for high speed wireless data.

Figure 1. Pin Configuration

ORDERING INFORMATION

PIN DESCRIPTIONS

ABSOLUTE MAXIMUM RATINGS

RECOMMENDED OPERATING CONDITIONS

NOTES:

1. There are no ESD protection diodes between pins 42, 43 and V_{CC} to allow higher AC peak voltage. The ESD protection level has thus been reduced. Proper ESD handling precautions should be followed.

MODE CONTROL

1. Sleep mode (PLL OFF, Rx OFF, Tx OFF)

In this mode everything is switched off except the 3–wire digital bus. As long as the digital supply is still on, the programmed values are active and the 3–wire bus will continue to be programmable.

2. Wait Mode (Tx Off, Rx Standby)

PLL is on. Receiver is in the reduced current standby mode and the transmitter is completely switched off. This mode maybe useful if the PLL is to be kept on and is waiting for a quick turn–on to either transmit or receive modes, especially when Rx outputs are AC coupled.

3. Transmit mode (Rx standby)

The PLL and transmitter are on. The receive section is in a reduced current mode wherein most of the Rx circuitry is powered down

except for the bias and baseband circuits needed to hold the baseband output voltages in the active state. This mode is useful if the Rx baseband outputs are AC coupled via a large capacitor and the application demands quick turn–on for the Rx, from Tx.

4. Receive Mode (Tx Off)

The Transmitter is completely shut–off. The PLL and receiver sections are operating.

5. Transmit Mode (Rx OFF)

PLL and Transmit sections are on. However, the Receiver is completely shut–down. This mode is useful if the Rx baseband outputs are DC coupled to the external world.

RX VGA CONTROL TABLE

DC ELECTRICAL CHARACTERISTICS

 V_{CC} XXX=+3V; V_{EE} XXX = 0V; TA=25°C, unless otherwise stated.

AC ELECTRICAL CHARACTERISTICS IF TRANSMIT MODULATOR

(Mode #3, Tx ON Rx Standby) $V_{\text{CC}}XXX = +3V$; GNDXXX = 0V; LO_in = 100 mV peak at 704 MHz, CLKin = 100mV peak at 22 MHz, T_{amb} = 25°C, unless otherwise stated.

NOTES:

1. Tx inputs are differential sine wave, 0.5 V peak, with quadrature relationship between I and Q Tx input. The output spectrum will be SSB. The tone is at a frequency of 1 MHz.

2. The output current in each arm is the same but 180 degrees out of phase with each other. Also the tuned load of 400 ohms differential, is assumed. The power delivered to 400 ohms will be –10.4 dBm (typ.). The output current measurement is indirect based on output power measurement according to P = 10 log I²rms (400Ω)/IMV. See typical performance characteristic curve.

3. This is measured with respect to the SSB output.

4. Guaranteed by design and or characterization but not final tested.

5. The input bandwidth may be verified by measuring the output THD and signal level using a DSB spectrum where I = Q.

6. Measured over temperature and supply.

AC ELECTRICAL CHARACTERISTICS IF RECEIVER DEMODULATOR

(Mode #4, Rx_ON, Tx_OFF) V_{CC} XXX = +3V = GNDXXX = 0V; LO IN = 100 m V_{peak} at 704 MHz, CLKIN = 100m V_{peak} , at 22 MHz, Ta = 25°C, unless otherwise stated.

NOTES:

1. The Receive input is to be differential (using a balun or a differential source such as a differential SAW filter) and matched to external generator's impedance (ex: 50 ohms). The balun may or may not provide any impedance transformation depending on availability. An external L–C matching circuit can provide the rest of the impedance transformation and absorb the input capacitance of the receiver input. Such a differential input scheme is mandatory to avoid pickup, and keep the noise figure low. A shunt resistor across the input (value TBD) will be used to set the input impedance as a compromise between the matching ease in production versus the noise figure of the receiver. The system board layout has to keep the isolation between the receive inputs and the LO signal as high as possible. Otherwise the LO leakage will overload the receiver.

2. The load is 1000 ohms in parallel with 15pF of capacitor.

3. THD is total harmonic distortion. We measure harmonics 2, 3, 4.

4. Guaranteed by design.

5. 3dB bandwidth relative to a passband measurement taken at 1MHz.

AC ELECTRICAL CHARACTERISTICS IF SYNTHESIZER

 V_{CC} XXX = RX_ON = TX_ON = PLL_ON = +3V, V_{EE} XXX = 0V; LO_IN = 100 m V_{peak} at 704 MHz, CLKIN = 100m V_{peak} at 22 MHz, Ta = 25°C, unless otherwise stated.

NOTES:

1. The relative output current variation is defined thus: $\frac{\Delta I_{\text{OUT}}}{I_{\text{OUT}}}$ = 2 $\cdot \frac{(I_2 - I_1)}{I(I_2 + 1)}$ $\frac{(2+1)}{11(2+1)}$; WITH V₁ = 0.7V, V₂ = V_{CC}CP – 0.8V (see Figure 3).

2. The output current matching is measured when both (positive current and negative current) sections of the output charge pumps are on

3. Guaranteed by design.

4. Maximum level guaranteed by design.

I 2 I 1 I 2 I 1 V_1 V_2 CURRENT VOLTAGE SR00526

Figure 3. Relative Output Current Variation

APPLICATION DESCRIPTION

General

The 1630 performs the IF modulator and demodulator functionality for high–speed wireless data transceivers. The design is optimized for IEEE 802.11 wireless LAN using 11 chips/symbol Direct Sequence Spread Spectrum.

Transmitter

The IF quadrature transmitter baseband modulator input is driven differentially by the D/A converters in the DSP chip. The baseband signals are DC coupled for fast turn–on and turn–off and for constant carrier testing. The typical common–mode input voltage is VCC/2.

The open collector outputs of the mixers are biased by two inductors, which are part of an LC tank. The LC tank matches the output impedance of the mixers to the input impedance of the upconverter chip (or any filter in between) and suppresses IF harmonics.

An optional 2.5V reference is available during mode (3) and (5), the transmit mode with Rx in standby. This reference can be enabled or disabled via the 3 wire bus (in this mode). This voltage is provided for use by an external current DAC if needed.

Receiver

The receiver part of the SA1630 consists of an IF Variable gain amplifier, a quadrature demodulator and a pair of baseband amplifiers. The IF amplifier has its gain controlled by the DSP chip. This ensures linear operation of the receiver chain over a wide dynamic range of input signals. Linear operation is essential for resolving echo's due to multipath reception.

The digital controlled AGC is meant for fast level training for the receiver.

The high gain receiver, which is distributed between the IF and baseband part facilitates interfacing with the RF front–end chip, which normally have moderate gains (up to 20 dB), and SAW IF filters, which mostly have considerable loss (up to 8 dB) without external amplifiers.

The baseband amplifiers have a high drive capability (1 Vpp into 1kΩ, 15 pF for VCC = 3V) that facilitates direct interfacing to the A/D converter without active external elements.

The baseband amplifiers can interface directly to the Track/Hold switch/capacitor combination with capacitance values up to 15 pF. When sampled at 22MHz the output can settle to within 1/4 LSB when swinging 1V p–p.

The chip has a unique mode in which the Rx is on standby while the Tx is ON. In this mode the Rx Baseband circuits are idling at reduced currents and all Rx I/O outputs retain their DC bias unchanged from their values when the Rx was fully ON. This mode is very essential if ac coupling through a large capacitor, such as, 10nF is used. From this mode the chip can quickly be switched to the Rx ON mode (Tx OFF) without worrying about charging/discharging the large AC coupling capacitor.

The VGA can be programmed in 2 ways: 1) Directly programming external control pins. 2) programming over the serial 3–wire bus. The former method can switch gain in less than 200 ns.

The Rx baseband section also incorporates simple low pass active filters of the Sallen key type. The Rx bandwidth is mainly set by these filters. The function of these filters is twofold: 1) attenuate high frequency signals from the Rx mixers. 2) act as anti–aliasing filters for any A to D converters following this chip.

IF synthesizer

The SA1630 has an integrated synthesizer that uses an external VCO operating on twice the IF frequency. It is internally divided by 2 for obtaining quadrature signals. The divided VCO signal is not externally available. This minimizes the LO feedthrough to the IF input port and hence minimizes output dc glitches when the IF gain is switched.

The PLL reference clock is derived from the 22 MHz DSP clock. The available divider ratios facilitate both 1 and 2 MHz phase comparison frequency from a 22 MHz and an optional 44 MHz clock respectively. In essence the reference divider will have programmable dividers ratios of 8, 11, 22 and 44.

The VCO shall be fed from a stabilized supply. Such a stabilized supply is necessary in order to prevent oscillator jitters due to Rx/Tx switching. The effect of oscillator jitters is further minimized when using a high PLL loop bandwidth, which on its turn requires a high phase comparison frequency (1 MHz, preferably 2 MHz).

If the IF Synthesizer is not used, the CLK_{IN} pins should be terminated to ac ground.

Serial Programming Input

The serial input is a 3–wire input (CLOCK, STROBE, DATA) to program the counter ratios, charge pump current, status– and DC–offset register, mode select and test register. The programming data is structured into two 21–bit words; each word includes 4 chip address bits and 1 subaddress bit. Figure 2 shows the timing diagram of the serial input. When the $STROBE = L$, the clock driver is enabled and on the positive edges of the CLOCK the signal on DATA input is clocked into a shift register. When the STROBE $=$ H, the clock is disabled and the data in the shift register remains stable. Depending on the value of the subaddress bit the data is latched into different working registers. Table 3 shows the contents of each word.

Default States

Upon power up $(V_{CC}DIG$ is applied) a reset signal is generated, which sets all registers to a default state. The logic level at the

STROBE pin should be low during power up to guarantee a proper reset. These default states are shown in Table 2.

Reference Divider

The reference divider can be programmed to four different division ratios (:8, :11, :22, :44), see registers r0, r1; default setting: divide by 22.

Main Divider

The external VCO signal, applied to the LO_{IN} and $LO_{IN}X$ inputs, is divided by two and then fed to the main divider (:N). The main divider is a programmable 9 bit divider, the minimum division ratio is divide by 64. The division ratio is binary coded and set in the registers n0 to n8. The default setting is a divide by 352.

At the completion of a main divider cycle, a main divider output is generated which will drive the phase detector.

Phase Detector

The phase detector is a D-type flip-flop phase and frequency detector shown in Figure 5. The flip-flops are set by the negative edges of the output signals of the dividers. The rising edge of the signal L will reset the flip-flops after both flip-flops have been set. Around zero phase error this has the effect of delaying the reset for 1 reference input cycle. This avoids non-linearity or deadband around zero phase error. The flip-flops drive on-chip charge pumps. A source current from the charge pump acts to increase the VCO frequency; a sink current acts to decrease the VCO frequency.

Current Setting

The charge pump current is defined by the current set between the pin I_{REF} and V_{EE} CP. The current value to be set there is 31.2 μ A. This current can be set by an external resistor to be connected between the pin I_{RFF} and V_{FF} CP. The typical value R_{FXT} (current setting resistor) can be calculated with the formula

$$
R_{\text{EXT}} = \frac{V_{\text{CC}}\text{CP}-1.6V}{31.2 \mu \text{A}} \ (44.87 \text{K for } 3\text{V})
$$

The current can be set to zero by connecting the pin I_{REF} to $V_{CC}CP$.

Charge Pumps

The charge pumps at pin CP are driven by the phase detector and the current value is determined by the binary value of the charge pumps register CN = c2, c1, c0, default .4mA. The active charge pump current is typically:

$$
|I_{CP}| = (c0 + 2c1 + 4c2) \cdot 29\mu A + 200\mu A
$$

Lock Detect

The output LOCK is H when the phase detector indicates a lock condition. This condition is defined as a phase difference of less than \pm 1 cycle on the reference input CLK_{IN}, CLK_{IN}X.

Test Modes (Synthesizer, Transmit Mixer)

The LOCK output is selectable as a test output. Bits x0, x1 control the selection, the default setting is normal lock output as described in the Lock detect section. The selection of a Bit x0, x1 combination has a twofold effect: First it routes a divider output signal to the LOCK pin, second it disables mixer stages in the transmit path. Setting $x0,1 = 11$ disables both transmit path mixers. This mode can be used to prevent the transmitter from producing an IF output signal even if the transmit part is powered on. This can be used to simplify the control timing while commanding the transmit and receive simultaneously without the transmit part causing interference.

Table 1. Test Modes

Table 2. Definition of SA1630 Serial Registers

Figure 4. Serial Input Timing Sequence

Figure 5. Phase Detector Structure with Timing

Figure 6. Typical SA1630 Test Circuit

Figure 10.

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

NOTES

Data sheet status

[1] Please consult the most recently issued datasheet before initiating or completing a design.

Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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